1. Background information
   1. Current walking robot specification overview
      1. Size
      2. Weight
      3. Max Speed
      4. Gaits
   2. Using pneumatics for walking robots vs hydraulics/electronics (taken from research folder) - Justin
   3. Design specifications and objectives based on research
      1. WHY we picked these specs and objectives (constraints excel document) - Ron
   4. Feasibility of electronic components for design requirements - tyler
2. Component design
   1. Microcontroller rekuhmendayshuns -tyler
   2. Proposed gaits -logan
   3. Leg layout/attachment
   4. Chassis design
3. Design Synthesis
   1. Proposed designs
   2. Design matrices
      1. Electrical
      2. Mechanical
      3. Software
   3. Design scores
   4. Proposed design
4. Final design
   1. Cool solidworks picture or something